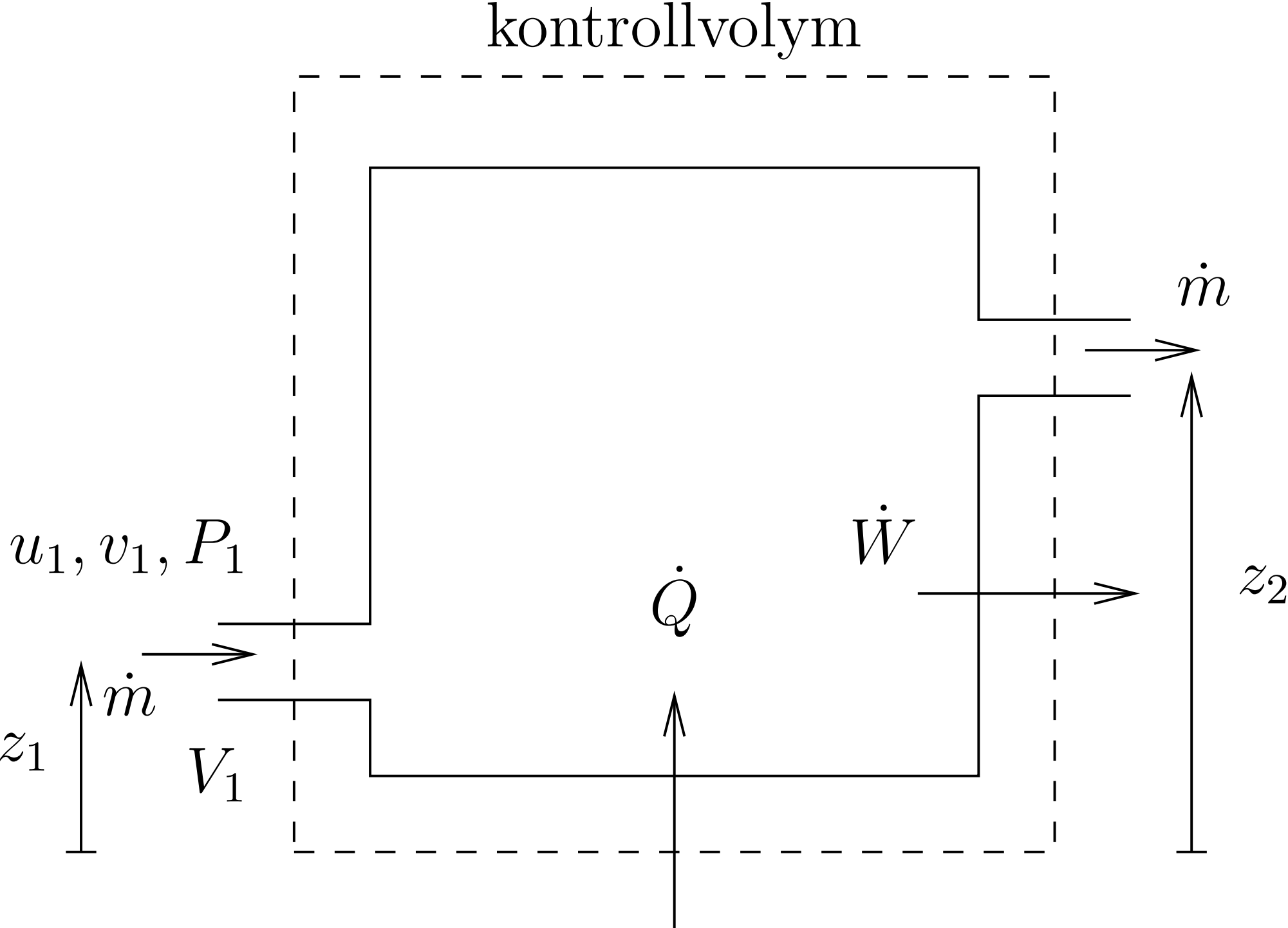
kontrollvolym
$\dot{m}$
u_1, v_1, P_1
$\dot{W}$
z_2
$\dot{Q}$
$\dot{m}$
z_1
V_1