

$m \bar{e}_R e_R =$

$$e_R = \frac{1}{2}(1 + \gamma_5)\psi$$

$$\bar{e}_R = e_R^\dagger \gamma^0 = \frac{1}{2} \psi^\dagger (1 + \gamma_5) \gamma^0 = \frac{1}{2} \underbrace{\psi^\dagger \gamma^0}_{=\bar{\psi}} (1 - \gamma_5)$$

$$\{\gamma^0, \gamma^5\} = 0; \quad \gamma^5 = i \gamma^0 \gamma^1 \gamma^2 \gamma^3$$

$m \bar{e}_R e_R = m \frac{1}{2} \bar{\psi} (1 - \gamma_5)(1 + \gamma_5)\psi$, and $(1 - \gamma_5)(1 + \gamma_5) = 0$. $m \bar{e}_R e_R = 0$.

$$m \bar{\psi} \psi = m(\bar{e}_R e_L + \bar{e}_L e_R)$$

In order to make a Dirac mass you need a Dirac spinor. This is possible in ordinary Dirac theory, but it is not allowed in the Standard Model, because of SU(2)

$$L_L = \begin{pmatrix} \nu_L \\ e_R \end{pmatrix}$$

Let us remind ourselves the content of the Standard Model.

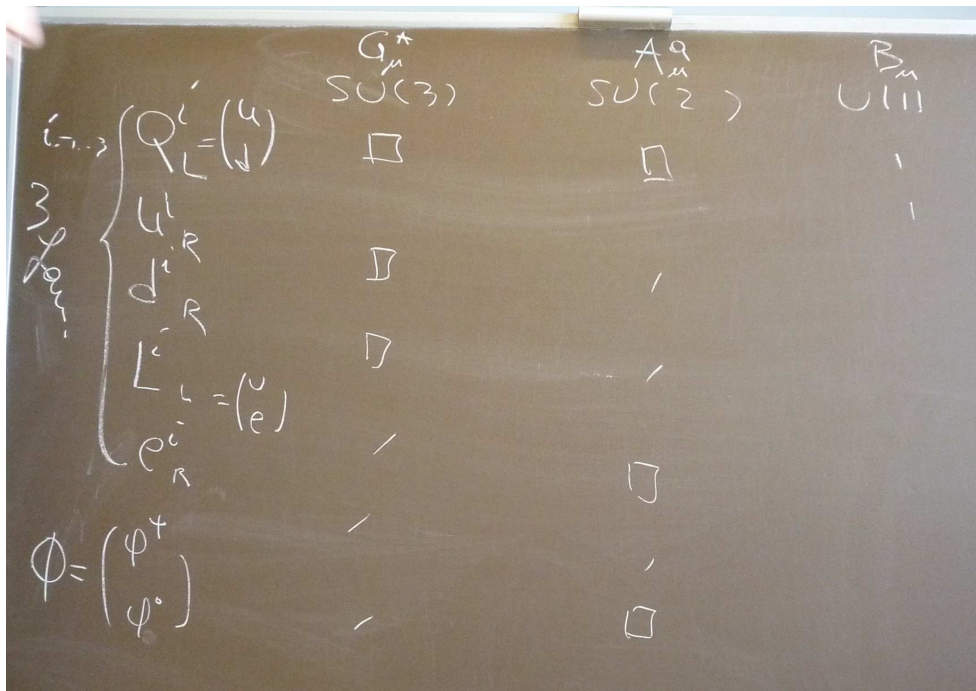


Figure 1.

$$L_L^a \Phi_a e_R$$

$\delta\psi = i g \tau^A \psi$ where $[\tau^A, \tau^B] = i f^{ABC} \tau^C$. f^{ABC} fixes the algebra. Define $\tilde{\tau}^A = -(\tau^A)^T$ (transpose, not dagger — $\tau^{A\dagger} = \tau^A$).

$$[\tilde{\tau}^A, \tilde{\tau}^B] = i f^{ABC} \tilde{\tau}^C$$

This is called a conjugate representation.

Take another field, so that $\delta\psi_a = i g \alpha^A(x) \tau^A_a{}^b \psi_b$ and $\delta\chi^a = i g \alpha^A(x) \tilde{\tau}^A_a{}^b \chi^b$. The fields with index up transform in the one representation, the fields with index down transform in the other representation.

$$\delta\psi\chi = \delta(\psi_a\chi^a) = 0$$

$$\begin{aligned} & \bar{L}_L^a \quad \Phi_a \quad e_R \\ & + \frac{1}{2} + \frac{1}{2} - 1 = 0 \end{aligned}$$

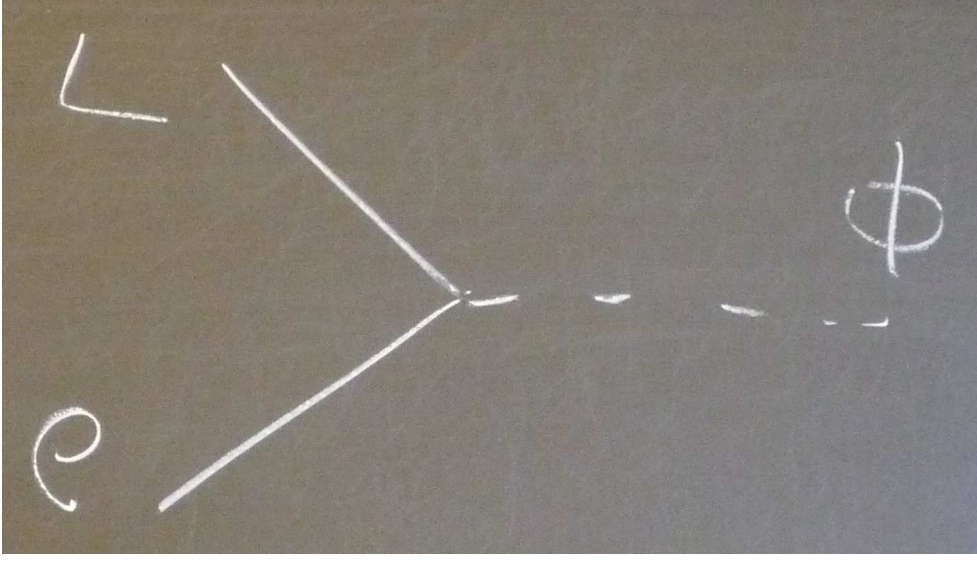


Figure 2. L, e, Φ

$$F^2 + \bar{\psi}\not{D}\psi + (D\phi)^2 + \bar{\psi}\phi\psi + \phi^2 + \phi^4$$

$$“\bar{\psi}\phi\psi” = -\lambda_{(d)}^{ij} \bar{Q}_L^{ai} \phi_a d_R^j - \lambda_{(u)}^{ij} \varepsilon_{ab} \bar{Q}_L^{ia} \phi^{\dagger b} u_R^j$$

Yukawa coupling λ : 3×3 matrix with no symmetry whatsoever. ε_{ab} is $\varepsilon_{11} = \varepsilon_{22} = 0, \varepsilon_{12} = -\varepsilon_{21} = 1$.

$$\phi^b \rightarrow g^b{}_c \phi^c, \quad Q^a \rightarrow g^a{}_b Q^b$$

$$\varepsilon_{ab} \phi^b Q^a \rightarrow \underbrace{\varepsilon_{ab} g^b{}_c g^a{}_d}_{=\det(g) \cdot \varepsilon_{cd}} \phi^c Q^d$$

The determinant in $SU(2)$ is one.

$$“\bar{\psi}\phi\psi” = -\lambda_{(d)}^{ij} \bar{Q}_L^{ai} \phi_a d_R^j - \lambda_{(u)}^{ij} \varepsilon_{ab} \bar{Q}_L^{ia} \phi^{\dagger b} u_R^j - \lambda_c^{ij} \bar{L}_L^{ia} \phi_a e_R^j - \lambda_\nu^{ij} \varepsilon_{ab} \bar{L}_L^{ia} \phi^{\dagger b} \nu_R^j$$

$$“\phi^2 + \phi^4” = -V(\phi)$$

$$\phi \rightarrow g_{2 \times 2} \phi, \quad \phi^\dagger \rightarrow \gamma^\dagger g^\dagger. \quad \phi^\dagger \phi \rightarrow \phi^\dagger g^\dagger g \phi = \phi^\dagger \phi.$$

$$“\phi^2 + \phi^4” = -V(\phi) = \mu^2 \phi^\dagger \phi - \lambda(\phi^\dagger \phi)^2$$

There are several minima. Choose $\phi_0 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ v \end{pmatrix}, v$ real

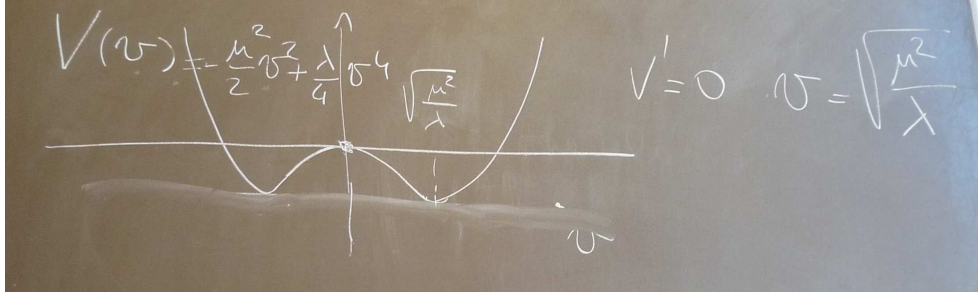


Figure 3.

$$v' = 0$$

$$246 \text{ GeV} = v = \sqrt{\frac{\mu^2}{\lambda}}$$

$$\begin{aligned} D_\mu \phi_0 &= \frac{1}{\sqrt{2}} \left(\partial_\mu \begin{pmatrix} 0 \\ v \end{pmatrix} - i g A_\mu^a \tau^a \begin{pmatrix} 0 \\ v \end{pmatrix} - i g' \frac{1}{2} B_\mu \begin{pmatrix} 0 \\ v \end{pmatrix} \right) = \\ &= \frac{1}{\sqrt{2}} \cdot \frac{1}{2} \begin{pmatrix} -i g A_\mu^3 - i g' B_\mu & -i g (A_\mu^1 - i A_\mu^2) \\ -i g (A_\mu^1 + i A_\mu^2) & +i g A_\mu^3 + i g' B_\mu \end{pmatrix} \begin{pmatrix} 0 \\ v \end{pmatrix} \end{aligned}$$

$$\begin{aligned} |D_\mu \phi_0|^2 &= \frac{1}{8} (0 \ v) \begin{pmatrix} g A_\mu^3 + g' B_\mu & g (A_\mu^1 - i A_\mu^2) \\ g (A_\mu^1 + i A_\mu^2) & -g A_\mu^3 + g' B_\mu \end{pmatrix} \begin{pmatrix} 0 \\ v \end{pmatrix} = \\ &= \frac{v^2}{8} (g^2 (A_\mu^1 + i A_\mu^2)(A_\mu^1 - i A_\mu^2) + (-g A_\mu^3 + g' B_\mu)^2) \end{aligned}$$

$$W_\mu^\pm = \frac{1}{\sqrt{2}} (A_\mu^1 \pm i A_\mu^2)$$

$$Z^0 = \frac{1}{\sqrt{g^2 + g'^2}} (g A_\mu^3 - g' B_\mu)$$

$$A_\mu = \frac{1}{\sqrt{g^2 + g'^2}} (g' A_\mu^3 + g B_\mu)$$

$$\begin{pmatrix} Z \\ A \end{pmatrix} = \frac{1}{\sqrt{g^2 + g'^2}} \begin{pmatrix} g & -g' \\ g' & g \end{pmatrix} \begin{pmatrix} A^3 \\ B \end{pmatrix} = \begin{pmatrix} \cos \theta_W & -\sin \theta_W \\ \sin \theta_W & \cos \theta_W \end{pmatrix} \begin{pmatrix} A^3 \\ B \end{pmatrix}$$

$$\mathcal{L}_{\text{mass}}^{\text{gauge}} = \underbrace{\frac{v^2 g^2}{4}}_{m_W^2} W_\mu^+ W^{\mu -} + \underbrace{\frac{v^2}{8} (g^2 + g'^2)}_{\frac{1}{2} m_Z^2} Z_\mu Z^\mu$$

$$D_\mu e_R = (\partial_\mu - i g' (-1) B_\mu) e_R = \left(\partial_\mu + i \frac{g'}{\sqrt{g^2 + g'^2}} (g' Z_\mu + g A_\mu) \right) e_R$$

$$|e| = \frac{g g'}{\sqrt{g^2 + g'^2}} = g \sin \theta_W = g' \cos \theta_W$$

$$D_\mu Q_L = \left(\partial_\mu - \text{gluons} - \frac{i g}{\sqrt{2}} (W^+ \tau^+ + W^- \tau^-) - i \frac{g}{\cos \theta_W} Z_\mu (\tau^3 - \sin^2 \theta_W Q) - i e A_\mu Q \right) Q_L$$

$$Q = \tau^3 + Y$$

eQ is the electric charge.

$$\begin{aligned} \text{“}\bar{\psi}\phi_0\psi\text{”} &= -\lambda_d^{ij} \bar{Q}_L^{ia} \phi_a d_R + \dots \\ &= \lambda_{(d)}^{ij} \left(\not{d}_L^i, \bar{d}_L^i \right) \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ v \end{pmatrix} d_R^j = -\lambda_{(d)}^{ij} \cdot \frac{1}{\sqrt{2}} v \cdot \bar{d}_L^i d_R^j \end{aligned}$$

Invariant under $SU(3)$ and $U(1)_{EM} \subset SU(2) \times U(1)$.

$$Qd_L = -\frac{1}{2} + \frac{1}{6}$$

$$Qd_R = 0 - \frac{1}{3}$$

$$\mathcal{L}_{\text{masses}}^{\text{fermi}} = -\frac{v}{\sqrt{2}} \left(\lambda_{(d)}^{ij} \bar{d}_L^i d_R^j \right) + \lambda_{(u)}^{ij} \bar{u}_L^i u_R^j + \lambda_{(e)}^{ij} e_L^i e_R^j + ?$$

Not the physical ones (yet). You have to diagonalise the quadratic part of the Lagrangian.